

## Homework 5 Supplemental Problem Solutions

1. The matrix  $S = \begin{bmatrix} 1/3 & 2/3 & 2/3 \\ 2/3 & 1/3 & -2/3 \\ 2/3 & -2/3 & 1/3 \end{bmatrix}$  is a reflection matrix. When a vector in  $\mathbb{R}^3$  is multiplied by this matrix, the effect is to reflect the vector in a certain plane. Find an equation for that plane.

(Hint: First try to find a normal vector to the plane. This is a vector  $v \in \mathbb{R}^3$  that gets flipped by reflection, i.e.  $Sv = -v$ . To find such a  $v$ , we follow a process similar to that of Supplemental Problem 2 from HW2, i.e.  $Sv = -v \Leftrightarrow Sv + v = 0 \Leftrightarrow (S + I)v = 0$ .)

To find a vector  $v$  such that  $Sv = -v$ , we solve the matrix equation  $(S + I)x = 0$ . The augmented matrix is

$$[S + I \mid 0] = \begin{bmatrix} 4/3 & 2/3 & 2/3 & 0 \\ 2/3 & 4/3 & -2/3 & 0 \\ 2/3 & -2/3 & 4/3 & 0 \end{bmatrix}$$

which row reduces to

$$\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

So we get  $x_1 = -x_3$  and  $x_2 = x_3$ , and our solutions are of the form

$$\left\{ x = \begin{bmatrix} -x_3 \\ x_3 \\ x_3 \end{bmatrix} \right\} = \left\{ x_3 \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

We're interested in any non-zero solution, so setting  $x_3 = 1$  we get

$$v = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}.$$

The plane that has  $v = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$  as a normal vector is all vectors  $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$

such that  $v \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$  which gives the condition  $-x + y + z = 0$ . This is the equation for our plane.

We can do a quick check to make sure this is correct. If we have a vector that lives in this plane, then reflecting across the plane should do nothing to that vector. That is, if  $w$  is a vector in this plane, then  $Sw = w$ , since  $Sw$  is the vector  $w$  reflected across the plane. The vector  $\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$  lies in this plane, and

$$Sw = \begin{bmatrix} 1/3 & 2/3 & 2/3 \\ 2/3 & 1/3 & -2/3 \\ 2/3 & -2/3 & 1/3 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6/3 \\ 3/3 \\ 3/3 \end{bmatrix} = w$$

So this is probably the right plane.

## 2. Sample Exam Question:

Let  $A = \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 2 & 0 & 4 & 1 & 1 \\ 3 & 0 & 6 & 1 & 2 \end{bmatrix}$ .

Consider the following vectors:

$$\begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ -1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 5 \\ 10 \\ 15 \end{bmatrix}, \begin{bmatrix} 6 \\ 11 \\ 16 \end{bmatrix}$$

(a) Determine which of the above vectors are in  $\mathcal{N}(A)$ .

$A$  is a  $(3 \times 5)$  matrix, so  $\mathcal{N}(A) \subseteq \mathbb{R}^5$ , so we only need to check the 5-dimensional vectors. To check if a  $v$  vector is in  $\mathcal{N}(A)$ , we

need only check that  $Av = 0$ . So, since  $A \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$  and

$$A \begin{bmatrix} 3 \\ 1 \\ -1 \\ -1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \text{ those two vectors are in } \mathcal{N}(A). \text{ However,}$$

$$A \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 6 \\ 11 \\ 16 \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \text{ so } \begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} \text{ is not in } \mathcal{N}(A).$$

(b) Determine which of the above vectors are in  $\mathcal{R}(A)$ .

$A$  is a  $(3 \times 5)$  matrix, so  $\mathcal{R}(A) \subseteq \mathbb{R}^3$ , so we only need to check the 3-dimensional vectors. We know that  $\mathcal{R}(A)$  is a subspace, so it

always contains the 0 vector, so  $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$  is in  $\mathcal{R}(A)$ . Also, we know

that  $\mathcal{R}(A)$  is equal to the column space, so any vector that we can identify as a linear combination of the columns of  $A$  is in  $\mathcal{R}(A)$ . So

$$\begin{bmatrix} 5 \\ 10 \\ 15 \end{bmatrix} = 5A_1 \text{ is in } \mathcal{R}(A), \text{ and } \begin{bmatrix} 6 \\ 11 \\ 16 \end{bmatrix} = 5A_1 + A_4 \text{ is in } \mathcal{R}(A).$$

To see if  $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  is in  $\mathcal{R}(A)$ , we check to see if the matrix equation

$$Ax = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \text{ is consistent. The augmented matrix } \begin{bmatrix} A & | & \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \end{bmatrix} \text{ row}$$

reduces to

$$\begin{bmatrix} 1 & 0 & 2 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

The last row tells us that this system is inconsistent, and so  $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  is not in  $\mathcal{R}(A)$ .

### 3. Sample Exam Question:

Describe the null space of the  $(2 \times 6)$  zero matrix as precisely as possible.

We let  $A = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ , the  $(2 \times 6)$  zero matrix. To find  $\mathcal{N}(A)$ , we solve  $Ax = 0$ . This gives us the augmented matrix  $[A \mid 0] = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$  which gives us the equations  $0 = 0$ . Thus there are no restrictions on  $x_1, \dots, x_6$ , and so every vector in  $\mathbb{R}^6$  is in the null space of  $A$ . Thus  $\mathcal{N}(A) = \mathbb{R}^6$ .