

Math 126 Basic Summary of Facts

Facts about Vectors, Curves and General 3D

Vector Basics:

$ \mathbf{v} = \sqrt{v_1^2 + v_2^2 + v_3^2}$	$c\mathbf{v} = \langle cv_1, cv_2, cv_3 \rangle$	$\frac{1}{ \mathbf{v} }\mathbf{v}$ = 'unit vector in direction of \mathbf{v} '										
$\mathbf{u} + \mathbf{v} = \langle u_1 + v_1, u_2 + v_2, u_3 + v_3 \rangle$	$\mathbf{u} \cdot \mathbf{v} = u_1v_1 + u_2v_2 + u_3v_3$	$\mathbf{u} \times \mathbf{v} =$	<table border="1" style="display: inline-table; border-collapse: collapse;"> <tr> <td style="padding: 2px 5px;">\mathbf{i}</td> <td style="padding: 2px 5px;">\mathbf{j}</td> <td style="padding: 2px 5px;">\mathbf{k}</td> </tr> <tr> <td style="padding: 2px 5px;">a_1</td> <td style="padding: 2px 5px;">a_2</td> <td style="padding: 2px 5px;">a_3</td> </tr> <tr> <td style="padding: 2px 5px;">b_1</td> <td style="padding: 2px 5px;">b_2</td> <td style="padding: 2px 5px;">b_3</td> </tr> </table>	\mathbf{i}	\mathbf{j}	\mathbf{k}	a_1	a_2	a_3	b_1	b_2	b_3
\mathbf{i}	\mathbf{j}	\mathbf{k}										
a_1	a_2	a_3										
b_1	b_2	b_3										
$\mathbf{u} \cdot \mathbf{v} = \mathbf{u} \mathbf{v} \cos(\theta)$	$\mathbf{u} \cdot \mathbf{v} = 0$ means orthogonal	θ is the angle if drawn tail to tail										
$ \mathbf{u} \times \mathbf{v} = \mathbf{u} \mathbf{v} \sin(\theta)$	$\mathbf{u} \times \mathbf{v}$ is orthogonal to both	$ \mathbf{u} \times \mathbf{v} $ = parallelogram area										
$\text{comp}_{\mathbf{a}}(\mathbf{b}) = \frac{\mathbf{a} \cdot \mathbf{b}}{ \mathbf{a} }$	$\text{proj}_{\mathbf{a}}(\mathbf{b}) = \frac{\mathbf{a} \cdot \mathbf{b}}{ \mathbf{a} ^2} \mathbf{a}$											

Comments: Know how to check/find vectors that are parallel or orthogonal. Be comfortable with computation, interpretations, and consequences.

Basic Lines, Planes and Surfaces (assume the constants a , b and c are positive in the last three rows):

Lines: $x = x_0 + at, y = y_0 + bt, z = z_0 + ct$	(x_0, y_0, z_0) = a point on the line $\langle a, b, c \rangle$ = a direction vector
Planes: $a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$	(x_0, y_0, z_0) = a point on the plane $\langle a, b, c \rangle$ = a normal vector
Cylinder: One variable 'missing'	Know basics of traces
Elliptical Paraboloid: $z = ax^2 + by^2$	Hyperbolic Paraboloid: $z = ax^2 - by^2$
Ellipsoid: $ax^2 + by^2 + cz^2 = 1$	Cone: $z^2 = ax^2 + by^2$
Hyperboloid of One Sheet: $ax^2 + by^2 - cz^2 = 1$	Hyperboloid of Two Sheets: $ax^2 + by^2 - cz^2 = -1$

Comments: You should be very good at finding lines/planes and naming basic shapes.

Basic Parametric and Polar in \mathbb{R}^2 :

$\langle \frac{dx}{dt}, \frac{dy}{dt} \rangle$ = a tangent vector	$\frac{dy}{dx} = \frac{dy/dt}{dx/dt}$
$x = r \cos(\theta)$	$y = r \sin(\theta)$
$x^2 + y^2 = r^2$	$\tan(\theta) = \frac{y}{x}$

Basic Parametric in \mathbb{R}^3 :

$\mathbf{r}'(t) = \langle \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \rangle$	$\mathbf{r}''(t) = \langle \frac{d^2x}{dt^2}, \frac{d^2y}{dt^2}, \frac{d^2z}{dt^2} \rangle$
$\int \mathbf{r}(t) dt = \left\langle \int x(t)dt, \int y(t)dt, \int z(t)dt \right\rangle$	Note: There are three constants of integration.
Arc Length = $\int_a^b \sqrt{(x'(t))^2 + (y'(t))^2 + (z'(t))^2} dt$	$s(t) = \int_0^t \sqrt{(x'(u))^2 + (y'(u))^2 + (z'(u))^2} du$
$\kappa(t) = \frac{ \mathbf{r}'(t) \times \mathbf{r}''(t) }{ \mathbf{r}'(t) ^3}$	$\kappa(x) = \frac{ f''(x) }{(1+f'(x)^2)^{3/2}}$ = '2D curvature'
$\mathbf{r}'(t) = \mathbf{v}(t)$ = velocity vector	$ \mathbf{r}'(t) = \mathbf{v}(t) $ = speed
$\mathbf{r}''(t) = \mathbf{a}(t)$ = acceleration	$\mathbf{r}(t) = \int \mathbf{v}(t) dt$ and $\mathbf{v}(t) = \int \mathbf{a}(t) dt$
$\mathbf{T}(t) = \frac{1}{ \mathbf{r}'(t) } \mathbf{r}'(t)$ = unit tangent	$\mathbf{N}(t) = \frac{1}{ \mathbf{T}'(t) } \mathbf{T}'(t)$ = principal unit normal
$a_T = \frac{\mathbf{r}'(t) \cdot \mathbf{r}''(t)}{ \mathbf{r}'(t) } = \frac{d}{dt} \mathbf{r}'(t) $	$a_N = \frac{ \mathbf{r}'(t) \times \mathbf{r}''(t) }{ \mathbf{r}'(t) } = \kappa(t) (\mathbf{r}'(t))^2$

Facts about Surfaces, Critical Points, and Double Integrals

Slopes on Surfaces.

Be able to find and graph the domain	Know the basics on level curves/contour maps
$f_x(x, y) = \frac{\partial z}{\partial x} =$ slope in x -direction	$f_y(x, y) = \frac{\partial z}{\partial y} =$ slope in y -direction
$z = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$	Tangent plane/linearization.
$f_{xx}(x, y) = \frac{\partial^2 z}{\partial x^2} =$ concavity in x -direction	$f_{yy}(x, y) = \frac{\partial^2 z}{\partial y^2} =$ concavity in y -direction
$f_{xy}(x, y) = \frac{\partial^2 z}{\partial y \partial x} =$ mixed second partial	$f_{xy}(x, y) = f_{yx}(x, y)$ (Clairaut's Theorem)
$D = f_{xx} \cdot f_{yy} - (f_{xy})^2 =$ measure of concavity	$D < 0$ means concavity changes (saddle)
$D > 0, f_{xx} > 0$ means concave up all directions	$D > 0, f_{xx} < 0$ means concave down all directions

Comments:

- To find critical points: Find f_x and f_y , set them BOTH equal to zero, then COMBINE the equations and solve for x and y .
- To classify critical points: Find f_{xx} , f_{yy} , and f_{xy} . At each critical point compute f_{xx} , f_{yy} , f_{xy} and D and make appropriate conclusions from the second derivative test.
- To find absolute max/min on a region: Find critical points inside the region. Then, over each boundary, substitution the xy -equation for the boundary into the surface to get a one variable function. Find the absolute max/min of the one variable function over each boundary. In the end, evaluate $f(x, y)$ at all the critical points inside the region and the critical numbers and endpoints (corners) on each boundary to find the largest and smallest output.

Volumes: $\iint_D f(x, y) dA =$ signed volume 'above' the xy -axis, 'below' $f(x, y)$ and inside the region D .

We also saw $\iint_D 1 dA =$ area of D .

To set up a double integral:

- (1) Solve for integrand ($z = f(x, y)$).
- (2) Draw given xy -equations in the xy -plane. (label intersections).
- (3) Draw xy -equations that occur from surface intersections.
- (4) Set up the double integral(s) using the region for D .

Options for set up:

$\iint_D f(x, y) dA = \int_a^b \int_{g(x)}^{h(x)} f(x, y) dy dx,$	$y = g(x) =$ bottom, $y = h(x) =$ top
$\iint_D f(x, y) dA = \int_c^d \int_{p(y)}^{q(y)} f(x, y) dx dy,$	$x = p(y) =$ left, $x = q(y) =$ right
$\iint_D f(x, y) dA = \int_\alpha^\beta \int_{w(\theta)}^{v(\theta)} f(r \cos(\theta), r \sin(\theta)) r dr d\theta,$	$r = w(\theta) =$ inner, $r = v(\theta) =$ outer

Center of Mass Application: If $\rho(x, y) =$ formula for density at a point in the region D , then

$$M = \text{total mass} = \iint_D \rho(x, y) dA, \quad \bar{x} = \frac{\iint_D x \rho(x, y) dA}{\iint_D \rho(x, y) dA} \quad \text{and} \quad \bar{y} = \frac{\iint_D y \rho(x, y) dA}{\iint_D \rho(x, y) dA}$$

Facts about Taylor Polynomials and Error Bounds

$$T_1(x) = \sum_{k=0}^1 \frac{f^{(k)}(b)}{k!} (x-b)^k = f(b) + f'(b)(x-b).$$

$$T_2(x) = \sum_{k=0}^2 \frac{f^{(k)}(b)}{k!} (x-b)^k = f(b) + f'(b)(x-b) + \frac{f''(b)}{2!} (x-b)^2.$$

$$T_3(x) = \sum_{k=0}^3 \frac{f^{(k)}(b)}{k!} (x-b)^k = f(b) + f'(b)(x-b) + \frac{f''(b)}{2!} (x-b)^2 + \frac{f'''(b)}{3!} (x-b)^3.$$

$$T_n(x) = \sum_{k=0}^n \frac{f^{(k)}(b)}{k!} (x-b)^k = f(b) + f'(b)(x-b) + \frac{f''(b)}{2!} (x-b)^2 + \cdots + \frac{f^{(n)}(b)}{n!} (x-b)^n.$$

Taylor inequalities

$$\text{ERROR} = |f(x) - T_1(x)| \leq \frac{M}{2!} |x-b|^2 \quad , \text{ where } |f''(x)| \leq M \text{ on the interval, and in general,}$$

$$\text{ERROR} = |f(x) - T_n(x)| \leq \frac{M}{(n+1)!} |x-b|^{n+1} \quad , \text{ where } |f^{(n+1)}(x)| \leq M \text{ on the interval.}$$

Three types of error questions:

Given an interval $[b-a, b+a]$, find the $T_n(x)$ error bound:

1. Find $|f^{(n+1)}(x)|$.
2. Determine a bound (a *tight* bound if possible) for $|f^{(n+1)}(x)| \leq M$ on the interval.
3. In Taylor's inequality $\frac{M}{(n+1)!} |x-b|^{n+1}$ replace M and replace x by an endpoint.

Find an interval so that $T_n(x)$ has a desired error:

1. Write $[b-a, b+a]$ and you will solve for a .
2. Find $|f^{(n+1)}(x)|$.
3. Determine a bound (a *tight* bound if possible) for $|f^{(n+1)}(x)| \leq M$ on the interval, this will involve the symbol a .
4. In Taylor's inequality $\frac{M}{(n+1)!} |x-b|^{n+1}$ replace M and replace x by an endpoint (this will involve the symbol a).
5. Then solve for a to get the desired error.

Given an interval $[b-a, b+a]$, find n so that $T_n(x)$ gives a desired error:

(There is no good general way to solve for the answer in this case, you just use trial and error).

1. Find the error for $n = 1$, then $n = 2$, then $n = 3$, etc. Once you get an error less than the desired error, you stop.
2. If you spot a pattern in the errors, then use the pattern to solve for the first time the error will be less than the desired error.

Facts about Taylor Series

$$\begin{aligned}
 e^x &= \sum_{k=0}^{\infty} \frac{1}{k!} x^k && = 1 + x + \frac{1}{2!}x^2 + \frac{1}{3!}x^3 + \dots \quad , \text{ for all } x. \\
 \sin(x) &= \sum_{k=0}^{\infty} \frac{(-1)^k}{(2k+1)!} x^{2k+1} && = x - \frac{1}{3!}x^3 + \frac{1}{5!}x^5 + \dots \quad , \text{ for all } x. \\
 \cos(x) &= \sum_{k=0}^{\infty} \frac{(-1)^k}{(2k)!} x^{2k} && = 1 - \frac{1}{2!}x^2 + \frac{1}{4!}x^4 + \dots \quad , \text{ for all } x. \\
 \frac{1}{1-x} &= \sum_{k=0}^{\infty} x^k && = 1 + x + x^2 + x^3 + \dots \quad , \text{ for } -1 < x < 1.
 \end{aligned}$$

Substituting into series (examples):

$$\begin{aligned}
 e^{2x^3} &= \sum_{k=0}^{\infty} \frac{1}{k!} 2^k x^{3k} && = 1 + 2x^3 + \frac{2^2}{2!}x^6 + \frac{2^3}{3!}x^9 + \dots \quad , \text{ for all } x. \\
 \sin(5x) &= \sum_{k=0}^{\infty} \frac{(-1)^k}{(2k+1)!} 5^{2k+1} x^{2k+1} && = 5x - \frac{5^3}{3!}x^3 + \frac{5^5}{5!}x^5 + \dots \quad , \text{ for all } x. \\
 \cos(x^2) &= \sum_{k=0}^{\infty} \frac{(-1)^k}{(2k)!} x^{4k} && = 1 - \frac{1}{2!}x^4 + \frac{1}{4!}x^8 + \dots \quad , \text{ for all } x. \\
 \frac{1}{1+3x} &= \sum_{k=0}^{\infty} (-3)^k x^k && = 1 - 3x + 3^2x^2 - 3^3x^3 + \dots \quad , \text{ for } -1 < -3x < 1.
 \end{aligned}$$

Multiplying out (examples):

$$\begin{aligned}
 x^3 e^x &= \sum_{k=0}^{\infty} \frac{1}{k!} x^{k+3} && = x^3 + x^4 + \frac{1}{2!}x^5 + \frac{1}{3!}x^6 + \dots \quad , \text{ for all } x. \\
 \frac{x^2}{1+2x} &= \sum_{k=0}^{\infty} (-2)^k x^{k+2} && = x^2 - 2x^3 + 2^2x^4 - 2^3x^5 + \dots \quad , \text{ for } -1 < 2x < 1.
 \end{aligned}$$

Integrating/Differentiating (examples):

$$\begin{aligned}
 -\ln(1-x) &= \int_0^x \frac{1}{1-t} dt = \sum_{k=0}^{\infty} \frac{1}{k+1} x^{k+1} && = x + \frac{1}{2}x^2 + \frac{1}{3}x^3 + \dots \quad , \text{ for } -1 < x < 1. \\
 \tan^{-1}(x) &= \int_0^x \frac{1}{1+t^2} dt = \sum_{k=0}^{\infty} \frac{(-1)^k}{2k+1} x^{2k+1} && = x - \frac{1}{3}x^3 + \frac{1}{5}x^5 - \dots \quad , \text{ for } -1 < x < 1. \\
 \int e^{x^3} dx &= C + \sum_{k=0}^{\infty} \frac{1}{k!} \frac{1}{3k+1} x^{3k+1} && = C + x + \frac{1}{2!(4)}x^4 + \frac{1}{3!(7)}x^7 + \dots \quad , \text{ for all } x. \\
 \frac{1}{(1-x)^2} &= \frac{d}{dx} \left(\frac{1}{1-x} \right) = \sum_{k=0}^{\infty} kx^{k-1} && = 1 + 2x + 3x^2 + 4x^3 + \dots \quad , \text{ for } -1 < x < 1
 \end{aligned}$$