

# Solutions to Math 308 F Spring 2016 Midterm 1

1. Solve the following system of three equations with five unknowns.

$$\begin{array}{ccccc} 2x_1 & + & x_2 & - & 3x_5 = -2 \\ x_2 & + & x_4 & + & 5x_5 = 6 \\ -3x_1 & + & x_3 & + & 2x_5 = -1 \end{array}$$

If the system is consistent, identify your particular solution and the homogeneous solution.

$$\left[ \begin{array}{ccccc|c} 2 & 1 & 0 & 0 & -3 & -2 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ -3 & 0 & 1 & 0 & 2 & -1 \end{array} \right] \xrightarrow{x_2} \left[ \begin{array}{ccccc|c} 2 & 1 & 0 & 0 & -3 & -2 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ -6 & 0 & 2 & 0 & 4 & -2 \end{array} \right] \xrightarrow{\times 3} \left[ \begin{array}{ccccc|c} 2 & 1 & 0 & 0 & -3 & -2 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ 0 & 0 & 2 & 0 & 12 & -6 \end{array} \right]$$

$$\xrightarrow{-1} \left[ \begin{array}{ccccc|c} 2 & 1 & 0 & 0 & -3 & -2 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ 0 & 3 & 2 & 0 & -5 & -8 \end{array} \right] \xrightarrow{-3} \left[ \begin{array}{ccccc|c} 2 & 0 & 0 & -1 & -8 & -8 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ 0 & 0 & 2 & -3 & -20 & -26 \end{array} \right] \xrightarrow{\times \frac{1}{2}}$$

$$\xrightarrow{\begin{array}{l} x_4 + x_5 \text{ are free} \\ \text{let } x_4 = s_1, x_5 = s_2 \end{array}} \left[ \begin{array}{ccccc|c} 1 & 0 & 0 & -\frac{1}{2} & -4 & -4 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ 0 & 0 & 1 & -\frac{3}{2} & -10 & -13 \end{array} \right]$$

$$\text{Row 3: } x_3 - \frac{3}{2}x_4 - 10x_5 = -13 \rightarrow x_3 = \frac{3}{2}s_1 + 10s_2 - 13$$

$$\text{Row 2: } x_2 + x_4 + 5x_5 = 6 \rightarrow x_2 = -s_1 - 5s_2 + 6$$

$$\text{Row 1: } x_1 - \frac{1}{2}x_4 - 4x_5 = -4 \rightarrow x_1 = \frac{1}{2}s_1 + 4s_2 - 4$$

The solution is

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} \frac{1}{2}s_1 + 4s_2 - 4 \\ -s_1 - 5s_2 + 6 \\ \frac{3}{2}s_1 + 10s_2 - 13 \\ s_1 \\ s_2 \end{bmatrix} = \begin{bmatrix} -4 \\ 6 \\ -13 \\ 0 \\ 0 \end{bmatrix}_P + \begin{bmatrix} \frac{1}{2} \\ -1 \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix}_{S_1} + \begin{bmatrix} 4 \\ -5 \\ 10 \\ 0 \\ 1 \end{bmatrix}_{S_2}$$

2. Determine if the following set of vectors are independent. If they are not, write one of them as a linear combination of the other.

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \\ 4 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 3 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ -2 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 3 \\ 4 \end{bmatrix} \right\}$$

Solve  $A\vec{x} = 0$ , columns of A are the given vectors

$$\rightarrow \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ -1 & 3 & -2 & 3 & 0 \\ 4 & -1 & 2 & 4 & 0 \end{bmatrix} \xrightarrow{x_1 \times -4} \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 7 & -6 & 8 & 0 \end{bmatrix} \xrightarrow{-7} \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 3 & 3 & 0 \\ 0 & 0 & 15 & 15 & 0 \end{bmatrix}$$

$$\xrightarrow{-5} \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 3 & 3 & 0 \\ 0 & 0 & 15 & 15 & 0 \end{bmatrix} \xrightarrow{\cdot \frac{1}{3}} \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

echelon form

$x_4$  is free so there are infinitely many solutions  
to  $A\vec{x} = 0$ . The vectors are not linearly independent.

Carrying on:

$$\rightarrow \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{-2} \begin{bmatrix} 1 & -2 & 0 & -3 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{3} \begin{bmatrix} 1 & -2 & 0 & -3 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 + x_4 = 0 \rightarrow x_1 = -s$$

$$x_2 + 2x_4 = 0 \rightarrow x_2 = -2s$$

$$x_3 + x_4 = 0 \rightarrow x_3 = -s$$

$$x_4 = s$$

$$\text{Take } s = 1 \text{ for example}$$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = -1 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} - 2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \end{bmatrix} = 0 \text{ so}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

reduced echelon form

3. Answer the questions about the following linear transformation.

$$T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \rightarrow \begin{bmatrix} 2x_1 - x_2 + x_3 \\ x_1 + 4x_2 - 2x_3 \end{bmatrix}$$

(a) What are the domain and codomain of  $T$ ? Which matrix represents  $T$ ?

Domain:  $\mathbb{R}^3$

Codomain:  $\mathbb{R}^2$

$$\text{Matrix } A = \begin{bmatrix} 2 & -1 & 1 \\ 1 & 4 & -2 \end{bmatrix}$$

(b) Is  $T$  onto?

Yes. The vectors  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \end{bmatrix}$  span

the codomain  $\mathbb{R}^2$  because there are at least two non-parallel (hence not linearly independent) vectors.

(c) Is  $T$  one-to one?

No. By a Thm. from Ch.3,  $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$  cannot be one-to-one when  $m > n$ . In this case,  $m = 3 > 2 = n$ .

4. (a) True or false? A set of two vectors is linearly dependent if and only if one is a scalar multiple of the other. Explain.

True. Linearly dependent means  $c_1\vec{u}_1 + c_2\vec{u}_2 = \vec{0}$   
 has a non zero solution. Then we can write  $\vec{u}_1 = -\frac{c_1}{c_2}\vec{u}_2$  or  $\vec{u}_2 = -\frac{c_1}{c_2}\vec{u}_1$ . Since one of  $c_i$  or  $c_2$  is non zero.  
 One is a scalar multiple of the other means  $\vec{u}_1 = \alpha\vec{u}_2$  or  $\vec{u}_2 = \beta\vec{u}_1$ . Then we have  $\vec{u}_1 - \alpha\vec{u}_2 = \vec{0}$  or  $-\beta\vec{u}_1 + \vec{u}_2 = \vec{0}$  so they are dependent.

- (b) True or False? If  $m > n$ , any set of  $m$  vectors in  $\mathbb{R}^n$  spans  $\mathbb{R}^n$ . Explain.

False. Let  $m=3, n=2$   
 $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \end{bmatrix} \right\}$  do not span  $\mathbb{R}^2$

- (c) Give an example of a non zero linear transformation  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  which is not onto. If such an example does not exist, explain why not.

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$   
 $\vec{x} \rightarrow \begin{bmatrix} x_1 + 2x_2 \\ -x_1 - 2x_2 \end{bmatrix}$  given by  $A = \begin{bmatrix} 1 & 2 \\ -1 & -2 \end{bmatrix}$   
 range is spanned by the parallel vectors  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \end{bmatrix}$  so it's not all of  $\mathbb{R}^2$ .

- (d) Give an example of a set of three vectors which are linearly independent and do not span  $\mathbb{R}^3$ . If such an example does not exist, explain why not.

Not possible by the Big Theorem.  
 In  $\mathbb{R}^n$ ,  $n$  vectors span  $\mathbb{R}^n$  if and only if they are independent.

- (e) Give an example of a linear system with more variables than equations that has no solution. If such an example does not exist, explain why not.

$$\begin{aligned} x_1 + x_2 + x_3 &= 2 \\ x_1 + x_2 + x_3 &= 3 \end{aligned}$$