

Solutions to Math 308 G Spring 2016 Midterm 1

1. Solve the following system of three equations with five unknowns.

$$\begin{aligned} 2x_1 + x_2 - 3x_5 &= -2 \\ x_2 + x_4 + 5x_5 &= 6 \\ -3x_1 + x_3 + 2x_5 &= -1 \end{aligned}$$

If the system is consistent, identify your particular solution and the homogenous solution.

$$\begin{bmatrix} 2 & 1 & 0 & 0 & -3 & -2 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ -3 & 0 & 1 & 0 & 2 & -1 \end{bmatrix} \xrightarrow{\begin{matrix} \times 2 \\ \times 2 \end{matrix}} \begin{bmatrix} 2 & 1 & 0 & 0 & -3 & -2 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ -6 & 0 & 2 & 0 & 4 & -2 \end{bmatrix} \xrightarrow{\times 3}$$

$$\rightarrow \begin{bmatrix} 2 & 1 & 0 & 0 & -3 & -2 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ 0 & 3 & 2 & 0 & -5 & -8 \end{bmatrix} \xrightarrow{\begin{matrix} -1 \\ -3 \end{matrix}} \begin{bmatrix} 2 & 0 & 0 & -1 & -8 & -8 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ 0 & 0 & 2 & -3 & -20 & -26 \end{bmatrix} \xrightarrow{\begin{matrix} \times \frac{1}{2} \\ \times \frac{1}{2} \end{matrix}}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 0 & -\frac{1}{2} & -4 & -4 \\ 0 & 1 & 0 & 1 & 5 & 6 \\ 0 & 0 & 1 & -\frac{3}{2} & -10 & -13 \end{bmatrix}$$

$x_4 + x_5$ are free

let $x_4 = s_1$, $x_5 = s_2$

Row 3: $x_3 - \frac{3}{2}x_4 - 10x_5 = -13 \rightarrow x_3 = \frac{3}{2}s_1 + 10s_2 - 13$

Row 2: $x_2 + x_4 + 5x_5 = 6 \rightarrow x_2 = -s_1 - 5s_2 + 6$

Row 1: $x_1 - \frac{1}{2}x_4 - 4x_5 = -4 \rightarrow x_1 = \frac{1}{2}s_1 + 4s_2 - 4$

The solution is

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} \frac{1}{2}s_1 + 4s_2 - 4 \\ -s_1 - 5s_2 + 6 \\ \frac{3}{2}s_1 + 10s_2 - 13 \\ s_1 \\ s_2 \end{bmatrix} = \underbrace{\begin{bmatrix} -4 \\ 6 \\ -13 \\ 0 \\ 0 \end{bmatrix}}_{\vec{x}_p} + \underbrace{\begin{bmatrix} \frac{1}{2} \\ -1 \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix}}_{\vec{x}_n} s_1 + \underbrace{\begin{bmatrix} 4 \\ -5 \\ 10 \\ 0 \\ 1 \end{bmatrix}}_{\vec{x}_n} s_2$$

2. Determine if the following set of vectors are independent. If they are not, write one of them as a linear combination of the other.

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \\ 4 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 3 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ -2 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 3 \\ 4 \end{bmatrix} \right\}$$

Solve $A\vec{x} = \vec{0}$, columns of A are the given vectors

$$\begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ -1 & 3 & -2 & 3 & 0 \\ 4 & -1 & 2 & 4 & 0 \end{bmatrix} \xrightarrow{x_1} \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 7 & -6 & 8 & 0 \end{bmatrix} \xrightarrow{-1} \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 3 & 3 & 0 \\ 0 & 0 & 15 & 15 & 0 \end{bmatrix} \xrightarrow{-7}$$

$$\begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 3 & 3 & 0 \\ 0 & 0 & 15 & 15 & 0 \end{bmatrix} \xrightarrow{-5} \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 3 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\times \frac{1}{3}} \begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

echelon form

x_4 is free so there are infinitely many solutions
 $A\vec{x} = \vec{0}$. The vectors are not linearly independent.

Carrying on:

$$\begin{bmatrix} 1 & -2 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{-2} \begin{bmatrix} 1 & -2 & 0 & -3 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{2} \begin{bmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned} x_1 + x_4 &= 0 \rightarrow x_1 = -x_4 \\ x_2 + 2x_4 &= 0 \rightarrow x_2 = -2x_4 \\ x_3 + x_4 &= 0 \rightarrow x_3 = -x_4 \\ x_4 &= s \end{aligned}$$

$$\vec{x} = \begin{bmatrix} -s \\ -2s \\ -s \\ s \end{bmatrix} = s \begin{bmatrix} -1 \\ -2 \\ -1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

reduced echelon form

Take $s=1$ for example

$$-1 \begin{bmatrix} 1 \\ 0 \\ -1 \\ 4 \end{bmatrix} - 2 \begin{bmatrix} -2 \\ 1 \\ 3 \\ -1 \end{bmatrix} - \begin{bmatrix} 2 \\ -3 \\ -2 \\ 2 \end{bmatrix} + \begin{bmatrix} -1 \\ -1 \\ 3 \\ 4 \end{bmatrix} = \vec{0}$$

$$\begin{bmatrix} -1 \\ 3 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 4 \end{bmatrix} + 2 \begin{bmatrix} -2 \\ 1 \\ 3 \\ -1 \end{bmatrix} + \begin{bmatrix} 2 \\ -3 \\ -2 \\ 2 \end{bmatrix}$$

3. Answer the questions about the following linear transformation.

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \rightarrow \begin{bmatrix} 2x_1 + x_2 \\ -x_1 + 4x_2 \\ x_1 - 2x_2 \end{bmatrix}$$

(a) What are the domain and codomain of T ? Which matrix represents T ?

Domain: \mathbb{R}^2
Codomain: \mathbb{R}^3

matrix $\begin{bmatrix} 2 & 1 \\ -1 & 4 \\ 1 & -2 \end{bmatrix}$

(b) Is T onto?

No, T cannot be onto by a Thm. from Chapter 3:
Any $T: \mathbb{R}^m \rightarrow \mathbb{R}^n$ cannot be onto when $m < n$.
In this case, $m=2 < n=3$.

(c) Is T one-to-one?

Yes. Solve $T\vec{x} = \vec{0}$

$$\begin{bmatrix} 2 & 1 & 0 \\ -1 & 4 & 0 \\ 1 & -2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 0 \\ -1 & 4 & 0 \\ 2 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 0 \\ 0 & 2 & 0 \\ 0 & 5 & 0 \end{bmatrix} \begin{matrix} \times \frac{1}{2} \\ \times \frac{1}{2} \\ \times \frac{1}{5} \end{matrix}$$

$$\rightarrow \begin{bmatrix} 1 & -2 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{matrix} \times 2 \\ \times -1 \\ \times -1 \end{matrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad x_1 = x_2 = 0 \quad \text{so } T \text{ is one-to-one}$$

OR the vectors $\begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 4 \\ -2 \end{bmatrix}$ are linearly

independent since one is not a scalar multiple of the other.

So $x_1 \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 4 \\ -2 \end{bmatrix} = \vec{0}$ has the unique solution $x_1 = x_2 = 0$

and T is one-to-one.

4. (a) True or false? A set of two vectors is linearly dependent if and only if one is a scalar multiple of the other. Explain.

True. Linearly dependent means $c_1 \vec{u}_1 + c_2 \vec{u}_2 = \vec{0}$ has a non-zero solution c_1, c_2 . Then we can write $\vec{u}_1 = -\frac{c_2}{c_1} \vec{u}_2$ or $\vec{u}_2 = -\frac{c_1}{c_2} \vec{u}_1$ since one of c_1 or c_2 is not zero. One is a scalar multiple of the other means $\vec{u}_1 = \alpha \vec{u}_2$ or $\vec{u}_2 = \beta \vec{u}_1$. Then we have $\vec{u}_1 - \alpha \vec{u}_2 = \vec{0}$ or $-\beta \vec{u}_1 + \vec{u}_2 = \vec{0}$, so they are dependent.

- (b) True or False? If $m > n$, any set of m vectors in \mathbb{R}^n spans \mathbb{R}^n . Explain.

False. Let $m=3, n=2$. Take vectors $\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \end{bmatrix}$ which do not span all of \mathbb{R}^2 (they span the line through $(0,0)$ and $(1,1)$)

- (c) Give an example of a non zero linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which is not one-to-one. If such an example does not exist, explain why not.

$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by $A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}$
 $T\left(\begin{bmatrix} 2 \\ -1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 2-2 \\ 6-6 \end{bmatrix} = \vec{0}$ so T is not one-to-one.

- (d) Give an example of a set of three vectors which are linearly dependent and span \mathbb{R}^3 . If such an example does not exist, explain why not.

Not possible. By the Big Theorem, n vectors span \mathbb{R}^n if and only if they are independent. In this case $n=3$.

- (e) Give an example of a linear system with fewer variables than equations that has infinitely many solutions. If such an example does not exist, explain why not.

$$\begin{aligned} x_1 + x_2 &= 1 \\ 2x_1 + 2x_2 &= 2 \\ 3x_1 + 3x_2 &= 3 \end{aligned} \quad \vec{x} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \end{bmatrix} s$$