

## CENTER OF GRAVITY

### LECTURE 5, EXERCISE SET 1

Recall that the group  $M$  of all rigid motions is generated by the following three “families” of elements:

- (1) Translations  $t_{\vec{a}}$  ( $t_{\vec{a}}\vec{v} = \vec{v} + \vec{a}$ )
- (2) Rotations around the origin counterclockwise  $\rho_\phi$ .  
Rotation preserves the origin, and can be described by a rotation matrix  $\rho_\phi = \begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix}$
- (3) And just ONE reflection  $r$  - reflection through (around, over, under or with or without respect to) the  $x$ -axis. The reflection  $r$  also fixes the origin and correspond to the matrix  $r = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ .

Any orientation-reversing rigid motion of the plane can be obtained by subsequent compositions of a reflection  $r$  followed by a rotation followed by a translation; for orientation-preserving motion skip the reflection.

**Definition.** Let  $s_1, \dots, s_n$  be  $n$  points on the plane. The *center of gravity* is the point whose coordinates are the arithmetic means of the coordinates of  $s_i$  :

$$p = \frac{s_1 + \dots + s_n}{n}$$

**Exercise.** Show that rigid motions preserve centers of gravity.

Hint: Since the group of all rigid motions is generated by translations, rotations and a reflection, it suffices to do the exercise for those three. So, here is a reformulation:

**Exercise 1.** Show that the following rigid motions preserve centers of gravity:

- (1) Rotation  $\rho_\phi$ ,
- (2) Translation  $t_{\vec{a}}$ ,
- (3) Reflection through the  $x$ -axis  $r$ .

Recall that we denote by  $M$  the group of all rigid motions of the plane. An (orthogonal) subgroup  $\mathbb{O} < M$  is the subgroup of all motions which fix the origin. A subgroup  $T < M$  is the subgroup of all translations of the plane.

**Definition.** A subgroup of  $M$  is called *discrete* if it does not contain arbitrarily small rotations or translations.

**Exercise 2.** Show that a discrete subgroup of  $M$  consisting of rotations around the origin is cyclic and is generated by some rotation  $\rho_\theta$ .

**Exercise 3.** Show that a discrete subgroup of  $\mathbb{O}$  is a finite group.