

## ORBITS

### LECTURE 6, EXERCISE SET 1

**Definition 1.** Let  $G$  be a group of motions of the plane (that is,  $G$  is a subgroup of  $M$ ), and  $s$  be a point. The *orbit* of  $s$  is the set of all points into which  $s$  can be transformed by the motions in  $G$ .

**Exercise 2.** Plot the orbits for the following points and groups:

- (1) For  $s = (1, 0)$ , and  $G = D_3$ ;
- (2) For  $s = (1, 2)$ , and  $G = D_4$ ;
- (3) For  $s = (\sqrt{3}, 1)$ ,  $G = D_6$

**Theorem 1.** (*Fixed Point Theorem.*) Let  $G$  be a finite group of rigid motions of the plane. There exists a point  $s$  on the plane which is fixed under the action of  $G$  (that is, any elements of the group  $G$  leaves  $s$  in place

**Exercise 3.** Consider a subgroup of  $M$  generated by two rotations: a rotation around the origin by the angle  $2\pi/5$ , and a rotation around the point  $(1, 1)$  by the angle  $\pi/3$ . Is this group finite or infinite?