

No books, notes or calculators are allowed. Show ALL your work.

- (30) 1. Mark each of the following statements true or false. You don't have to give an explanation.
- (a) $\det AB = \det A \cdot \det B$
 - (b) $\det(A + B) = \det A + \det B$
 - (c) $\det A = \det A^{-1}$
 - (d) If A is invertible, then A^T is invertible
 - (e) If A is an invertible square matrix of dimension $n \times n$, then $\text{rk } A = n$.
 - (f) $AB = BA$
 - (g) If $\det A \neq \det B$, then A and B cannot be row equivalent
 - (h) $\text{rk } A^T = \text{rk } A$
 - (i) If A is an invertible matrix $n \times n$, then $Ax = b$ is consistent for any $b \in \mathbf{R}^n$
 - (j) If a vector space V has dimension n , then any set of n vectors in V form a basis

Solution.

- (a) True
- (b) False
- (c) False
- (d) True
- (e) True
- (f) False
- (g) True
- (h) True
- (i) True
- (j) False

(25) 2. (a) Check that vectors

$$\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}, \text{ and } \begin{bmatrix} 1 \\ 0 \\ 7 \end{bmatrix}$$

form a basis of \mathbf{R}^3 .

(b) Find coordinates of the vector $\begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix}$ with respect to the basis above.

Solution.

(a) Compute determinant of the matrix $A = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 0 & 0 \\ 0 & 1 & 7 \end{bmatrix}$ by decomposing with respect to the second row. We get $\det A = 13$. Since $\det A \neq 0$, the matrix is invertible and its columns are linearly independent. Thus, they form a basis.

(b) Solve the system

$$\begin{bmatrix} 1 & 2 & 1 & 2 \\ -1 & 0 & 0 & -1 \\ 0 & 1 & 7 & 6 \end{bmatrix}$$

by row reduction. We get $(1, 1/13, 11/13)$.

- (20) 3. Compute the volume of a parallelepiped with vertices $(1, 0, 1)$, $(2, 1, 2)$, $(2, 2, 5)$, $(2, -3, 10)$, $(3, 3, 6)$, $(3, -1, 14)$, $(3, -2, 11)$, $(4, 0, 15)$.

Solution.

Shifting by the vector $(1, 0, 1)$, we get a parallelepiped with one vertex at the origin, based on vectors $(1, 1, 1)$, $(1, 2, 4)$, and $(1, -3, 9)$.

$$\text{Volume} = \det \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & -3 \\ 1 & 4 & 9 \end{bmatrix} = 20$$

- (25) 4. Let $T : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ be a linear transformation.
- (a) Define what it means for T to be *onto*.
 - (b) Suppose the kernel of T is a line. Can T be onto? Explain.
 - (c) Define what it means for T to be *one-to-one*.
 - (d) Suppose T is a projection onto the x -axis. Is T one-to-one? Describe $\text{Ker } T$ geometrically.
 - (e) Let T be a rotation by 90° counterclockwise. Write the matrix of T . Explain why T is onto and one-to-one.

Solution.

(b) No. By the Rank Theorem, $\dim \text{Ker } T + \dim \text{Im } T = 2$. Since $\dim \text{Ker } T = 1$, we conclude that $\dim \text{Im } T = 1$. But for T to be onto, image of T has to be the entire \mathbf{R}^2 which has dimension 2.

(d) No. Projection is not one-to-one, because all vectors of the form $(0, y)$ map to zero. Kernel of T is the y -axis, which is a line.

(e) $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$. Matrix is invertible, therefore, T is onto and one-to-one.

- (30) 5. (a) Define basis and dimension of a vector space V .
 (b) Determine whether the set of vectors $1+t+t^3, 2t^2-t^3, 3-2t-t^2+2t^3, 4+4t+t^2+3t^3$ forms a basis of the vector space P_3 , i.e. the space of all real polynomials of degree at most 3. State the dimension of this vector space.

Solution.

(b) The standard basis of P_3 is given by polynomials $(1, t, t^2, t^3)$. With respect to the standard basis, new vectors have coordinates $(1, 1, 0, 1)$, $(0, 0, 2, -1)$, $(3, -2, -1, 2)$, and $(4, 4, 1, 3)$. We compute the determinant of the matrix with corresponding columns:

$$\det \begin{bmatrix} 1 & 0 & 3 & 4 \\ 1 & 0 & -2 & 4 \\ 0 & 2 & -1 & 1 \\ 1 & -1 & 2 & 3 \end{bmatrix} = \det \begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 0 & -5 & 0 \\ 0 & 2 & -1 & 1 \\ 1 & -1 & 2 & 3 \end{bmatrix} = -5 \cdot \det \begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 0 & 1 & 0 \\ 0 & 2 & -1 & 1 \\ 1 & -1 & 2 & 3 \end{bmatrix} = -5 \cdot$$

$$\det \begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 0 & 1 & 0 \\ 0 & 2 & -1 & 1 \\ 0 & -1 & -1 & -1 \end{bmatrix} = 5 \cdot \det \begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 0 & 1 & 0 \\ 0 & 2 & -1 & 1 \\ 0 & 1 & 1 & 1 \end{bmatrix} = 5 \cdot \det \begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 2 & -1 & 1 \end{bmatrix} = 5 \cdot$$

$$\det \begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -3 & -1 \end{bmatrix} = 5 \cdot \det \begin{bmatrix} 1 & 0 & 3 & 4 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} = -5. \text{ Since } \det \neq 0, \text{ vectors are lin-}$$

early independent. The dimension of P_3 is 4, because the standard basis has 4 elements. Since the new set consists of 4 linearly independent vectors, the Basis theorem implies that they form a basis.

(25) 6. Let A be a matrix of dimension $m \times n$. Finish the equalities

(a) $\text{rk } A + \dim \text{Nul } A =$

(b) $\text{rk } A + \dim \text{Nul } A^T =$

(c) Using (a) and (b), show that a square matrix A is invertible if and only if A^T is invertible.

Solution.

(a) $\text{rk } A + \dim \text{Nul } A = n$

(b) $\text{rk } A + \dim \text{Nul } A^T = m$

(c) Let A be $n \times n$. In this case, (a) + (b) implies that $\dim \text{Nul } A = \dim \text{Nul } A^T$. A is invertible if and only if $Ax = 0$ does not have non-trivial solutions if and only if $\dim \text{Nul } A = 0$ if and only if $\dim \text{Nul } A^T = 0$ if and only if $A^T x = 0$ does not have non-trivial solutions if and only if A^T is invertible.

- (25) 7. (a) Let $A = \begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix}$, $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$. Using Cramer's rule, solve matrix equations $Ax_1 = e_1$, $Ax_2 = e_2$.
- (b) What is A^{-1} ?
- (c) Let A be an arbitrary invertible matrix 2×2 and e_1, e_2 be as in (a). Let x_1, x_2 be the solutions of the matrix equations $Ax_1 = e_1$ and $Ax_2 = e_2$. Explain why x_1, x_2 are linearly independent.

Solution.

(a) $\det A = 1$.

For $Ax_1 = e_1$, $\det A_1(e_1) = -1$, $\det A_2(e_2) = -2$.

For $Ax_2 = e_2$, $\det A_1(e_2) = 1$, $\det A_2(e_2) = 1$.

Applying Cramer's formula, we obtain

$$x_1 = \begin{bmatrix} -1 \\ -2 \end{bmatrix}, \quad x_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

(b) $A^{-1} = [x_1 \ x_2] = \begin{bmatrix} -1 & 1 \\ -2 & 1 \end{bmatrix}$

(c) Observe that $A \cdot [x_1 \ x_2] = [e_1 \ e_2] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$. Thus, $A^{-1} = [x_1 \ x_2]$. As columns of the invertible matrix A^{-1} , x_1, x_2 must be linearly independent.

Alternatively, one may observe that if x_1, x_2 satisfy some non-trivial linear relation, i.e. $ax_1 + bx_2 = 0$, then e_1, e_2 satisfy the same linear relation since $ae_1 + be_2 = aAx_1 + bAx_2 = A(ax_1 + bx_2) = A(0) = 0$. But this is impossible, since e_1, e_2 form the standard basis in \mathbf{R}^2 and, in particular, are linearly independent.

- (25) 8. (a) Define kernel of a linear transformation $T : V \rightarrow W$.
(b) Show that $\text{Ker } T$ is always a subspace of V .

(c) Let T be a linear transformation of \mathbf{R}^3 given by the matrix $A = \begin{bmatrix} 0 & -1 & 2 \\ 1 & 3 & -5 \\ 1 & 2 & -3 \end{bmatrix}$.

Find basis and dimension of $\text{Ker } T$.

Solution.

(a) $\text{Ker } T = \{x \in V : T(x) = 0\}$.

(b) If $x, y \in \text{Ker } T$, then $T(x) = T(y) = 0$. Therefore, $T(x+y) = T(x) + T(y) = 0 + 0 = 0$. Thus, $x + y \in \text{Ker } T$. We conclude that $\text{Ker } T$ is closed under addition. Similarly, if $T(x) = 0$, then $T(cx) = cT(x) = 0$ for any real number c . Thus, $\text{Ker } T$ is closed under scalar multiplication. Now it is a subspace by definition.

(c) $\text{Ker } T = \text{Nul } A$. To find basis of $\text{Nul } A$, we solve homogeneous system $Ax = 0$. The solutions are $z \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$. Thus, $\begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$ is a basis of $\text{Nul } A$, and dimension is 1.