

1. Find the Schmidt decomposition and the singular value decomposition of the matrix $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}$.

NEXT TIME GET A BETTER MATRIX (easier singular values)

2. Solve the initial value problem

$$\begin{aligned} \frac{dx_1}{dt} + 2x_1 - x_2 &= 0 & x_1(0) &= 6 \\ \frac{dx_2}{dt} - x_1 + 2x_2 &= 0 & x_2(0) &= 7 \end{aligned}$$

as follows:

- (i) Write the problem in vector form:

$$\frac{d}{dt}X + A \cdot X = O \quad X(0) = \begin{pmatrix} 6 \\ 7 \end{pmatrix}.$$

- (ii) Find an orthonormal basis of eigenvectors of the matrix A .
 (iii) Find two independent solutions $X = X_1(t)$ and $X = X_2(t)$ of $dX/dt + A \cdot X = O$ with

$$X_1(t) = f_1(t)B_1 \text{ and } X_2(t) = f_2(t)B_2,$$

where $\{B_1, B_2\}$ is an orthonormal basis of \mathbb{R}^2 , and f_1 and f_2 are real valued functions.

- (iv) Using (ii), write the general solution in the form

$$X(t) = B \cdot \begin{pmatrix} e^{-\lambda_1 t} & 0 \\ 0 & e^{-\lambda_2 t} \end{pmatrix} \cdot \begin{pmatrix} c_1 \\ c_2 \end{pmatrix},$$

where the columns of B are B_1 and B_2 .

- (v) Show that $\begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = B^t \cdot \begin{pmatrix} 6 \\ 7 \end{pmatrix}$.

- (vi) Put this all together to write the solution in the form

$$X(t) = B \cdot \begin{pmatrix} e^{-\lambda_1 t} & 0 \\ 0 & e^{-\lambda_2 t} \end{pmatrix} \cdot B^t \cdot X_0$$

3. Solve the initial value problem

$$\begin{aligned} x'_1 &= x_2 + x_3, & x_1(0) &= 3 \\ x'_2 &= x_1 + x_3, & x_2(0) &= 0 \\ x'_3 &= x_1 + x_2, & x_3(0) &= 0 \end{aligned}$$

by finding an orthonormal basis of eigenvectors of the appropriate matrix.

Hint: $t^3 - 3t - 2 = (t - 2)(t + 1)^2$

4. Let $A = \begin{pmatrix} 0 & -c & b \\ c & 0 & -a \\ -b & a & 0 \end{pmatrix}$ be a non-zero 3×3 skew symmetric matrix.

- (i) Show that the characteristic polynomial of A is of the form

$$p_A(t) = t^3 + (a^2 + b^2 + c^2)t = t(t - \lambda_1)(t - \lambda_2) = t(t^2 - (\lambda_1 + \lambda_2)t + \lambda_1\lambda_2),$$

and from this conclude that the spectrum of A is of the form $\{0, \lambda_1, \lambda_2\}$, with

$$\lambda_1 + \lambda_2 = 0 \text{ and } \lambda_1\lambda_2 = a^2 + b^2 + c^2, .$$

Conclude that $\lambda_1 = i\omega$ and $\lambda_2 = -i\omega$, with $\omega = \sqrt{a^2 + b^2 + c^2}$

(ii) Let $B_1 = \frac{1}{\omega} \begin{pmatrix} a \\ b \\ c \end{pmatrix}$. Show that $A \cdot B_1 = 0$.

(iii) Let $B_2 + iB_3$ satisfy

$$A \cdot (B_2 + iB_3) = i\omega(B_2 + iB_3) \implies A \cdot B_2 = -\omega B_3 \text{ and } A \cdot B_3 = \omega B_2$$

Prove that $\|B_2\| = \|B_3\|$ and $\langle B_1, B_2 \rangle = \langle B_1, B_3 \rangle = \langle B_2, B_3 \rangle = 0$. Hence, (after rescaling B_2 and B_3 if necessary) $\{B_1, B_2, B_3\}$ is an orthogonal basis for \mathbb{R}^3 with respect to the standard scalar product.

Hint: Show that $X^t \cdot A \cdot X = 0$ for any vector; then show that for $i \neq j$, the scalar product $\langle B_i, B_j \rangle$ can be expressed as a multiple of $X^t A X$ for $X = B_i$ or $X = B_j$.

(iv) Use these facts to prove that

$$R_t = \exp(tA) = B \cdot \exp \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & \omega t \\ 0 & -\omega t & 0 \end{pmatrix} \cdot B^t = B \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos(\omega t) & \sin(\omega t) \\ 0 & -\sin(\omega t) & \cos(\omega t) \end{pmatrix} \cdot B^t.$$

In particular, R_t is a clockwise rotation by ωt radians about the vector B_1 :

$$R_t \cdot B_1 = B_1, \quad R_t(B_2) = \cos(\omega t)B_2 - \sin(\omega t)B_3, \quad R_t(B_3) = \sin(\omega t)B_2 + \cos(\omega t)B_3.$$

5. Which of the matrices below are diagonalizable? In each case, give a one or two sentence explanation for your answer.

$$(a) \begin{pmatrix} 3 & 1 & 4 & 5 \\ 0 & 2 & 4 & 2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 7 \end{pmatrix} \quad (b) \begin{pmatrix} 3 & 1 & 1 & 1 \\ 1 & 4 & 2 & 1 \\ 1 & 2 & 4 & 5 \\ 1 & 1 & 5 & 7 \end{pmatrix} \quad (c) \begin{pmatrix} 2 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

6. What is the shape of the set of all solutions to the equation

$$4x^2 - 2xy + 4y^2 = 1?$$

7. Find the Cholesky decomposition of the following matrix.

$$A = \begin{pmatrix} 4 & 2 & -2 & 2 \\ 2 & 26 & 13 & 1 \\ -2 & 13 & 14 & -1 \\ 2 & 1 & -1 & 10 \end{pmatrix}$$

8. Use your answer to the previous problem to solve $Ax = (1 \ 2 \ 3 \ 4)^T$