# Lecture 10-11: Jordan decomposition continued and commutative groups

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Lecture 10-11: Jordan decomposition con

Image: A matrix

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I now tie the Jordan decomposition to algebraic groups. Given such a group G and  $g \in G$ , we have seen that right translation  $\rho(g)$  by g on  $\mathbf{k}[G]$  (acting via the recipe  $(\rho(g)f)(x) = f(xg)$ ) is locally finite, so we have a unique Jordan decomposition  $\rho(g) = \rho(g)_{s}\rho(g)_{u}$ 

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#### Theorem 2.4.8, p. 34: Jordan decomposition in G

Given  $g \in G$  there are unique  $g_s, g_u \in G$  with  $\rho(g_s) = \rho(g)_s, \rho(g_u) = \rho(g)_u, g = g_s g_u = g_u g_s$ . If  $\phi : G \to G'$  is a homomorphism, then  $\phi(g_s) = \phi(g)_s, \phi(g_u) = \phi(g)_u$ . If  $G = GL_n(\mathbf{k})$ , then  $g = g_s g_u$  is the Jordan decomposition of G defined previously.

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Since  $\rho(g)$  is an algebra automorphism of  $\mathbf{k}[G]$ , it commutes with addition and multiplication in  $\mathbf{k}[G]$ , whence by a property of the Jordan decomposition proved last time so do  $\rho(g)_s, \rho(g)_u$ . Given a k-algebra homomorphism of  $\mathbf{k}[G]$  into k, corresponding to an element of G, its compositions with  $\rho(g)_{s}\rho(g)_{\mu}$  thus also correspond to commuting elements  $g_s, g_u$  of G, respectively, with  $q = q_s q_{\mu}$ . Uniqueness follows since  $\rho$  is faithful on G. Given a homomorphism  $\phi$  it factors as a surjective homomorphism onto its image followed by an inclusion of this image into G'. Again previous properties of the Jordan decomposition yield the second assertion. The third one follows similarly.

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We say that  $g \in G$  is semisimple if  $g = g_s$  and similarly that  $g \in G$  is unipotent if  $g = g_u$ . It follows at once that  $g \in G$  is semisimple if and only if  $\phi(g)$  is semisimple as a matrix for any homomorphism  $\phi : G \to GL(n, \mathbf{k})$ ; similarly for unipotent elements. We also deduce a significant constraint on closed (or equivalently algebraic) subgroups of  $GL(n, \mathbf{k})$ : any such subgroup must contain the semisimple and unipotent parts of all of its elements.

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## Proposition 2.4.12, p. 36

If G is a subgroup of  $GL_n$  consisting of unipotent matrices, then there is  $x \in GL_n$  with  $xGx^{-1} \subset U_n$ , the subgroup of upper triangular unipotent matrices.

We call any such subgroup *unipotent*; by above results unipotent algebraic groups are exactly those consisting of unipotent elements, or conjugate to a subgroup of  $U_n$ .

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We know that G acts linearly on  $V = \mathbf{k}^n$ . If there is a proper subspace W of V stabilized by G, then the result at once by induction on dim V. If there is no such subspace, then G acts irreducibly on V. Then it is well known that linear combinations of matrices in G fill out all of  $M_n$ , the algebra of  $n \times n$  matrices over **k**. Any matrix in G has trace n, whence the trace of (1 - g)h is 0 for all  $g, h \in G$ , whence also for  $g \in G, h \in M_p$ . Since the trace form on  $M_p$  sending any ordered pair(x, y) of matrices to the trace of their product xy is nondegenerate, so that no nonzero matrix is orthogonal to every other under this form, this forces G = 1 and the result is trivial.

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Next I show that unipotent groups act on affine varieties with closed orbits.

Proposition 2.4.14, p. 37

If G is unipotent and X is an affine G-space, then all orbits of G on X are closed.

Let *O* be a *G*-orbit. Replacing *X* by the closure  $\overline{O}$  we may assume that *O* is dense in *X* and then we know that *O* is also open in *X*. Letting *Y* be the complement of *O* in *X*, we have that *G* acts locally finitely on the ideal of functions in  $\mathbf{k}[X]$  vanishing on *Y*, whence if *Y* is nonempty there is a nonzero function *f* vanishing on *Y* and fixed by *G*, which must be constant on *O* and thus on *X*. This is a contradiction, forcing O = X, as desired.

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Skipping the rest of Chapter 2 (pp. 37-41) we proceed to Chapter 3, treating commutative algebraic groups.

## Theorem 3.1.1, p. 42

Let G be a commutative algebraic group. The sets  $G_s$ ,  $G_u$  of semisimple and unipotent elements of G are closed subgroups and G is isomorphic to their direct product. If G is connected so are  $G_x$  and  $G_u$ .

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We may assume G is a closed subgroup of some  $GL_n$ . Since the product of two commuting semisimple (resp. unipotent) elements of G is again semisimple (resp. unipotent), we see that  $G_{\rm s}, G_{\rm u}$  are subgroups with product G. Since a commuting family of semisimple matrices is conjugate to a subset of the set  $D_n$  of diagonal matrices, we can arrange things so that G lies in the the subgroup  $T_n$  of upper triangular matrices and  $G_s$  is its intersection with the subgroup  $D_n$  of diagonal matrices, whence  $G_s$  is closed; likewise  $G_u = G \cap U_n$  is closed. The uniqueness of the Jordan decomposition shows that the product map  $\pi: G_s \times G_u \to G$  is an isomorphism of abstract groups, while the map sending g to  $g_s$  picks out the diagonal entries of g, so is a morphism. Hence  $\pi$  is an isomorphism of algebraic groups, as claimed. Finally, if G is connected then so are its images  $G_s, G_u$ under the projection maps.

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I now specialize to (algebraic) groups of dimension one.

## Proposition 3.1.3, p. 42

Any group G of dimension one is commutative, and either equal to  $G_s$  or  $G_u$ . If  $G = G_u$  and **k** has characteristic p > 0, then all elements of G have order dividing p.

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Fix  $g \in G$  and let  $\phi: G \to G$  send x to  $g^{-1}xg$ . The closure  $\overline{\phi G}$  is then an irreducible closed subset of G; since G has dimension one it must be a singleton or all of G. If it is all of G then the image  $\phi G$ , being open in G, must contain all but finitely many elements of G. Viewing G as a closed subgroup of some  $GL_n$ , this forces the set of characteristic polynomials det(T.1 - x) to be a finite set as x runs over G. The connectedness of G then implies that every  $x \in G$  has characteristic polynomial  $(T-1)^n$  and G is unipotent, forcing  $G \subset U_n$  after replacing G by a conjugate. Letting  $G_1 = [G, G]$ , the commutator subgroup of G, and  $G_2 = [G_1, G_1]$ , etc., we must have  $G_n = 1$  and yet  $G_1$  is either 1 or all of G, forcing  $G_1 = 1$  and G is commutative. The product  $G = G_x \times G_u$  forces  $G = G_s$  or  $G = G_u$ . Finally, if  $G = G_u$  and p > 0, then the set  $G^{p^k}$  of  $p^k$ -th powers of elements of G is a subgroup, which must be trivial if  $p^k > n$ , forcing  $G^p = 1$ , as desired.

I conclude with the definitions of torus (different from the one a topologist or geometer would use) and vector group.

# Definitions 3.2.1, p. 43 and 3.4.1, p. 51

An (algebraic) *torus* is a group isomorphic to  $D_n \cong G_m^n$  for some n; recall that  $G_m = \mathbf{k}^*$  is the multiplicative group of nonzero elements of  $\mathbf{k}$ . Likewise a *vector group* is one isomorphic to  $\mathbf{k}^n \cong G_a^n$ , where  $G_a = \mathbf{k}$ , considered as an additive group.

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