

On the Interchange of Subdifferentiation and Conditional Expectation for Convex Functionals

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We show that the operators $E^{\mathcal{G}}$ (conditional expectation given a σ -field \mathcal{G}) and ∂ (subdifferentiation), when applied to a normal convex integrand f , commute if the effective domain multifunction $\omega \rightarrow \{x \in R^n | f(\omega, x) < +\infty\}$ is \mathcal{G} -measurable.

We deal with interchange of conditional expectation and subdifferentiation in the context of stochastic convex analysis. The purpose is to give a condition that allows the commuting of these two operators when applied to convex integral functionals.

Let (Ω, \mathcal{A}, P) be a probability space, \mathcal{G} a σ -field contained in \mathcal{A} , and f an \mathcal{A} -normal convex integrand defined on $\Omega \times R^n$ with values in $R \cup \{\infty\}$. The latter means that the map

$$\omega \mapsto \text{epi} f(\omega, \cdot) = \{(x, \alpha) \in R^{n+1} | \alpha \geq f(\omega, x)\}$$

is a closed-convex-valued \mathcal{A} -measurable multifunction. See [2] and [9] for more on normal integrands and their properties. In particular recall that for any \mathcal{A} -measurable function $x: \Omega \rightarrow R^n$, the function

$$\omega \mapsto f(\omega, x(\omega))$$

is a \mathcal{A} -measurable and the integral functional associated with f is defined by

$$I_f(x) = \int f(\omega, x(\omega)) P(d\omega).$$

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To bypass some trivialities we impose the following summability conditions:

- (1) there exists a \mathcal{G} -measurable $x: \Omega \rightarrow R^n$ such that $I_f(x)$ is finite,
- (2) there exists $v \in \mathcal{L}_n^1(\mathcal{G}) = \mathcal{L}^1(\Omega, \mathcal{G}, P; R^n)$ such that $I_{f^*}(v)$ is finite,

where f^* is the (\mathcal{A} -normal) conjugate convex integrand, i.e.

$$f^*(\omega, x) = \sup_{v \in R^n} [v \cdot x - f(\omega, x)]$$

Finally, we assume that \mathcal{A} - and hence also \mathcal{G} - is countably generated, and that there exists a *regular* conditional probability (given \mathcal{G}), $P^{\mathcal{G}}: \mathcal{A} \times \Omega \rightarrow [0, 1]$. Whenever we refer to the conditional expectation given \mathcal{G} , we always mean the version obtained by integrating with respect to $P^{\mathcal{G}}$. Consequently all conditional expectations will be regular.

In particular the conditional expectation $E^{\mathcal{G}}f$ of f is the \mathcal{G} -normal integrand defined by

$$(E^{\mathcal{G}}f)(\omega, x) = \int f(\zeta, x) P^{\mathcal{G}}(d\zeta | \omega)$$

Also given $\Gamma: \Omega \rightrightarrows R^n$, a closed-valued \mathcal{A} -measurable multifunction, its conditional expectation given \mathcal{G} is a closed-valued \mathcal{G} -measurable multifunction obtained via a projection-type operation from a set

$$\mathcal{L}_{\Gamma}^1 = \{u \in \mathcal{L}^1(\Omega, \mathcal{A}, P; R^n) | u(\omega) \in \Gamma(\omega) \text{ a.s.}\} \subset \mathcal{L}_n^1(\mathcal{A})$$

onto $\mathcal{L}_n^1(\mathcal{G})\Gamma = \mathcal{L}^1(\Omega, \mathcal{G}, P; R^n)$. Valadier has shown that a regular version $E^{\mathcal{G}}\Gamma: \Omega \rightarrow R^n$ is given by the expression

$$E^{\mathcal{G}}\Gamma(\omega) = cl\{\int u(\zeta) P^{\mathcal{G}}(d\zeta | \omega) | u \in \mathcal{L}_n^1(\mathcal{A}), u(\omega) \in \Gamma(\omega) \text{ a.s.}\}.$$

We refer to [14] and the references given therein for the properties of $E^{\mathcal{G}}f$; in particular to the article of Dynkin and Estigneev [3], which specifically deals with regular conditional expectations of measurable multifunctions.

We consider I_f and $I_{E^{\mathcal{G}}f}$ as (integral) functionals on $\mathcal{L}_n^{\infty}(\mathcal{A})$ and $\mathcal{L}_n^{\infty}(\mathcal{G})$ respectively. The natural pairings of \mathcal{L}^{∞} and \mathcal{L}^1 and $(\mathcal{L}^{\infty})^*$ yield for each functional two different subgradient multifunctions. We shall use ∂I_f and $\partial I_{E^{\mathcal{G}}f}$ for designating \mathcal{L}^1 -subgradients and $\partial^* I_f$ and $\partial^* I_{E^{\mathcal{G}}f}$ for $(\mathcal{L}^{\infty})^*$ -subgradients. Rockafellar [8, Corollary 1B] shows that when the summability conditions (1) and (2) are satisfied, one has the following representation for $(\mathcal{L}^{\infty})^*$ -subgradients:

$$\partial^* I_f(x) = \{v + v_s \mid v \in I_f(x), v_s \in \mathcal{L}_n^1(\mathcal{A}) \text{ with } v_s[x - x'] \leq 0 \forall x' \in \text{dom } I_f\} \tag{3}$$

where $\mathcal{L}_n^1(\mathcal{A})$ is the space of singular continuous linear functionals on $\mathcal{L}_n^\infty(\mathcal{A})$, and

$$\text{dom } I_f = \{x \in \mathcal{L}_n^\infty(\mathcal{A}) \mid I_f(x) < +\infty\}$$

is the effective domain of I_f . (For the decomposition of $(\mathcal{L}_n^\infty)^*$ consult [2, Chapter VIII]). Furthermore the \mathcal{L}^1 -subgradient set is given by

$$\partial I_f(x) = \{v \in \mathcal{L}_n^1(\mathcal{A}) \mid v(\omega) \in \partial f(\omega, x(\omega)) \text{ a.s.}\} \tag{4}$$

The summability conditions (1) and (2) on f imply similar properties for $E^{\mathcal{G}}f$, so the formulas above also apply to $I_{E^{\mathcal{G}}f}$. Thus for $x \in \mathcal{L}_n^\infty(\mathcal{G})$ we get

$$\partial^* I_{E^{\mathcal{G}}f}(x) = \{u + u_s \mid u \in \partial I_{E^{\mathcal{G}}f}(x), u_s \in \mathcal{L}_n^1(\mathcal{G}) \text{ with } u_s[x - x'] \geq 0, \forall x' \in \text{dom } I_{E^{\mathcal{G}}f}\} \tag{5}$$

and

$$\partial I_{E^{\mathcal{G}}f}(x) = \{u \in \mathcal{L}_n^1(\mathcal{G}) \mid u(\omega) \in \partial E^{\mathcal{G}}f(\omega, x(\omega)) \text{ a.s.}\} \tag{6}$$

We are interested in the relationship between ∂I_f and $\partial I_{E^{\mathcal{G}}f}$. Relying on the formulas just given, Castaing and Valadier [2, Theorem VIII.37] show that if in place of the summability conditions (1) and (2), one makes the stronger assumption:

there exists $x^\circ \in \mathcal{L}_n^\infty(\mathcal{G})$ at which I_f is finite and norm continuous, (7)

then for every $x \in \mathcal{L}_n^\infty(\mathcal{G})$ one gets:

$$\partial I_{E^{\mathcal{G}}f}(x) = E^{\mathcal{G}}(\partial I_f(x)) + rc[\partial I_{E^{\mathcal{G}}f}(x)], \tag{8}$$

where rc denotes the recession (or asymptotic) cone [2, 7]. If $x \in \text{int dom } I_{E^{\mathcal{G}}f}$, $\partial I_{E^{\mathcal{G}}f}(x)$ is weakly compact and then $rc[\partial I_{E^{\mathcal{G}}f}(x)] = \{0\}$, in which case

$$\partial I_{E^{\mathcal{G}}f}(x) = E^{\mathcal{G}}\partial I_f(x). \tag{9}$$

This was already observed by Bismut [1, Theorem 4]. For the subspace of

\mathcal{L}_n^∞ of constant functions, Hiriart-Urruty [4] obtain a similar result for the ε -subdifferentials of convex functions. For finite-valued Lipschitz integrands, Thibault [12, Proposition 4.7] obtained recently a related result involving Clarke generalized subgradients.

Here we shall go one step further and provide a condition under which the rc term can be dropped from the identity (8) without requiring that $x \in \text{int dom } I_f$. Very simple examples show that the rc term is sometimes inescapable in (8). For instance, suppose $\mathcal{G} = \{\phi, \Omega\}$ (so $E^\mathcal{G} = E$) and consider $f(\omega, \cdot) = \psi_{(-\infty, \xi(\omega)]}$, the indicator of the unbounded interval $(-\infty, \xi(\omega)]$, where ξ is a random variable uniformly distributed on $[0, 1]$. In this case $\psi_{(-\infty, 0]} = Ef = E^\mathcal{G}f = I_{E^\mathcal{G}f}$, so that $\partial I_{E^\mathcal{G}f}(0) = R_+$ but $E^\mathcal{G}(\partial I_f(0)) = E\{0\} = \{0\}$. Thus (8) would fail without the rc term. Another example appears in [13, p. 63] where it is the condition of the Theorem: "If $(x) < +\infty$ for every $x \in \mathcal{L}_n^\infty(\mathcal{G})$ such that $x(\omega) \in \text{dom } f(\omega, \cdot)$ ", that fails to be satisfied.

THEOREM *Suppose f is an \mathcal{A} -normal convex integrand such that the closure of its effective domain multifunction*

$$\omega \mapsto D(\omega) := \text{cl dom } f(\omega, \cdot) = \text{cl}\{x \in R^n \mid f(\omega, x) < +\infty\} \tag{10}$$

is \mathcal{G} -measurable. Assume that $I_f(x) < +\infty$ for every $x \in \mathcal{L}_n^\infty(\mathcal{G})$ such that $x(\omega) \in \text{dom } f(\omega, \cdot)$ a.s., and that there exists $x^0 \in \mathcal{L}_n^\infty(\mathcal{G})$ at which I_f is finite and norm continuous. Then for every $x \in \mathcal{L}_n^\infty(\mathcal{G})$ one has

$$\partial E^\mathcal{G}f(\cdot, x(\cdot)) = E^\mathcal{G} \partial f(\cdot, x(\cdot)) \text{ a.s.}, \tag{11}$$

or in other words, the closed-valued \mathcal{G} -measurable multifunctions

$$\omega \mapsto \partial E^\mathcal{G}f(\omega, x(\omega))$$

and

$$\omega \mapsto E^\mathcal{G}[\partial f(\cdot, x(\cdot))](\omega)$$

are almost surely equal.

Proof. From (8) it follows that

$$\partial I_{E^\mathcal{G}f}(x) \supset E^\mathcal{G}(\partial I_f(x)).$$

In view of (6) and (4) this holds if and only if

$$\partial E^\mathcal{G}f(\cdot, x(\cdot)) \supset E^\mathcal{G} \partial f(\cdot, x(\cdot)) \text{ a.s.}$$

It thus suffices to prove the reverse inclusion. Let us suppose that $u \in \partial E^\mathcal{G}f(\cdot, x(\cdot))$. For every $y \in R^n$, define

$$g(\omega, y) = f(\omega, y) - u(\omega) \cdot y.$$

This is an \mathcal{A} -normal convex integrand which inherits all the properties assumed for f in the Theorem (recall that $u \in \mathcal{L}_n^1(\mathcal{G})$). Moreover $0 \in \partial E^g(\cdot, x(\cdot))$. We shall show that $0 \in E^g \partial g(\cdot, x(\cdot))$, which in turn will imply that $u \in E^g \partial f(\cdot, x(\cdot))$ and thereby complete the proof of the Theorem.

Since almost surely $0 \in \partial E^g(\omega, x(\omega))$, we know that $0 \in \partial I_{E^g}(x) \subset \partial^* I_{E^g}(x)$. Hence x minimizes I_{E^g} on $\mathcal{L}_n^x(\mathcal{G})$. Let inj denote the natural injection of $\mathcal{L}_n^x(\mathcal{G})$ into $\mathcal{L}_n^x(\mathcal{A})$ with

$$\mathcal{W} = \text{inj} [\mathcal{L}_n^x(\mathcal{G})].$$

Now note that $\text{inj } x = x$ also minimizes I_{E^g} on $\mathcal{W} \subset \mathcal{L}_n^x(\mathcal{A})$, or equivalently I_g on \mathcal{W} , since the two integral functionals coincide on \mathcal{W} (by the definition of conditional expectation.) Thus

$$0 \in \partial^*(I_g + \psi_{\mathcal{W}})(x),$$

where $\psi_{\mathcal{W}}$ is the indicator function of \mathcal{W} , or equivalently:

$$0 \in \partial^* I_g(x) + \partial^* \psi_{\mathcal{W}}(x),$$

since g is (norm) continuous at some $x^0 = \text{inj } x^0 \in \mathcal{W}$. By (3), this means that there exist $v \in \mathcal{L}_n^1(\mathcal{A})$, $v_s \in \mathcal{L}_n(\mathcal{A})$, such that

$$v(\omega) \in \partial g(\omega, x(\omega)) \text{ a.s.}, \tag{12}$$

$$v_s[x - x'] \geq 0 \quad \text{for all } x' \in \text{dom } I_g, \tag{13}$$

and $-(v + v_s)$ is orthogonal to \mathcal{W} , i.e.

$$(v + v_s)[x'] = 0 \quad \text{for all } x' \in \mathcal{W}. \tag{14}$$

This last relation can also be expressed as

$$(v + v_s)[\text{inj } y] = 0 \quad \text{for all } y \in \mathcal{L}_n^x(\mathcal{G}),$$

or still for all $y \in \mathcal{L}_n^x(\mathcal{G})$

$$\text{inj}^*(v + v_s)[y] = 0,$$

where $\text{inj}^*: (\mathcal{L}_n^x(\mathcal{A}))^* \rightarrow (\mathcal{L}_n^x(\mathcal{G}))^*$ is the adjoint of inj . Thus the continuous linear functional $\text{inj}^*(v + v_s)$ must be identically 0 on $\mathcal{L}_n^x(\mathcal{G})$, i.e. on $\mathcal{L}_n^x(\mathcal{G})$

one has

$$\text{inj}^* v_s = -\text{inj}^* v = -E^{\mathcal{G}} v. \quad (15)$$

The last equality follows from the observation that $E^{\mathcal{G}} = \text{inj}^*$ when inj^* is restricted to $\mathcal{L}_n^1(\mathcal{A})$, cf. [2, p.265] for example.

We shall complete the proof by showing that the assumptions (12), (13) and (15) imply that

$$(v - E^{\mathcal{G}} v)(\omega) \in \partial g(\omega, x(\omega)) \text{ a.s.} \quad (16)$$

This will certainly do, since it trivially yields the sought-for relation

$$0 = E^{\mathcal{G}}(v - E^{\mathcal{G}} v) \in E^{\mathcal{G}} \partial g(\cdot, x(\cdot)).$$

To obtain (16), it will be sufficient to show that

$$E\{(-E^{\mathcal{G}} v) \cdot [x - y]\} \geq 0 \quad (17)$$

for all $y \in \text{dom } I_g \subset \mathcal{L}_n^{\infty}(\mathcal{A})$. To see this, recall that the relations (17) and $v \in \partial I_g(x)$ (cf. (12)) imply that $v - E^{\mathcal{G}} v \in \partial I_g(x)$, from which (16) follows via the representation of \mathcal{L}^1 -subgradients given by (4). In fact, because the effective domain multifunction, or more precisely its closure $\omega \mapsto D(\omega)$, is \mathcal{G} -measurable, it is sufficient to show that (17) holds for every $y \in \text{dom } I_g \cap \mathcal{W}$. Suppose to the contrary that (17) holds for every $y \in \text{dom } I_g \cap \mathcal{W}$ -- or equivalently because of the \leq inequality that (17) holds for every $y \in \text{cl dom } I_g \cap \mathcal{W}$ -- but there exists $\hat{y} \in \mathcal{L}_n^{\infty}(\mathcal{A})$ such that $I_g(\hat{y}) < +\infty$ and for which (17) fails, i.e. we have

$$E\{(-E^{\mathcal{G}} v) \cdot [x - \hat{y}]\} < 0.$$

Because $-E^{\mathcal{G}} v$ and x are \mathcal{G} -measurable, this inequality implies that

$$E\{(-E^{\mathcal{G}} v) \cdot [-E^{\mathcal{G}} \hat{y}]\} < 0. \quad (18)$$

Moreover, since $I_g(\hat{y}) < +\infty$, it follows that almost surely

$$\hat{y}(\omega) \in \text{dom } g(\omega, \cdot) \subset D(\omega).$$

Taking conditional expectation on both sides, we see that

$$(E^{\mathcal{G}} \hat{y})(\omega) \in E^{\mathcal{G}} D(\omega) = D(\omega), \quad (19)$$

because D is a closed-value \mathcal{G} -measurable multifunction. Naturally $E^{\mathcal{G}}\hat{y} \in \mathcal{W}$. Because I_g is by assumption finite on $\{z \in \mathcal{L}_n^{\infty}(\mathcal{G}) \mid z(\omega) \in \text{dom } g(\omega, \cdot) \text{ a.s.}\}$, and $D(\omega) = \text{cl dom } g(\omega, \cdot)$, it follows from (19) that $E^{\mathcal{G}}\hat{y} \in \text{cl dom } I_g$. Hence (17) cannot hold for every $y \in \text{dom } I_g \cap \mathcal{W}$ since $E^{\mathcal{G}}\hat{y}$ belongs to $(\text{cl dom } I_g) \cap \mathcal{W}$ and satisfies (18).

There remains only to show that (17) holds for every $y \in \mathcal{L}_n^{\infty}(\mathcal{G})$ such that $\text{inj } y = y \in \text{dom } I_g$. But now from (13) we have that for each such y

$$v_s[x - y] = v_s[\text{inj } x - \text{inj } y] \geq 0,$$

or again equivalently: for each $y \in \text{dom } I_g \cap \mathcal{L}_n^{\infty}(\mathcal{G})$,

$$(\text{inj}^* v_s)[x - y] \geq 0.$$

But this is precisely (17), since we know from (15) that on $\mathcal{L}_n^{\infty}(\mathcal{G})$, $\text{inj}^* v_s = -E^{\mathcal{G}}v$. \square

COROLLARY Suppose f is a \mathcal{A} -normal convex integrand such that $F(x) < +\infty$ whenever $x \in \text{dom } f(\omega, \cdot)$ a.s., where

$$F(x) = E\{f(\omega, x)\}.$$

Suppose moreover that there exists $x^0 \in R^n$ at which F is finite and continuous, and that the multifunction

$$\omega \mapsto D(\omega) = \text{cl dom } f(\omega, \cdot)$$

is almost surely constant. Then for all $x \in R^n$,

$$E[\hat{\partial}f(\cdot, x)] = \hat{\partial}F(x), \tag{20}$$

where the expectation of the closed-valued measurable multifunction Γ is defined by

$$E\Gamma = \text{cl}\left\{ \int v(\omega)P(d\omega) \mid v \in \mathcal{L}_n^1(\mathcal{A}), v(\omega) \in \Gamma(\omega) \text{ a.s.} \right\}$$

Proof Just apply the Theorem with $G = \{\phi, \Omega\}$, and identify the class of constant functions--the \mathcal{G} -measurable functions--with R^n . \square

This Corollary was first derived by Ioffe and Tikhomirov [5] and later generalized by Levin [6]. Note that our definition of the expectation of a closed-valued measurable multifunction is at variance with the definition now in vogue for the integral of a measurable multifunction, which does not involve the closure operation. (Otherwise the definition of the integral of a multifunction would be inconsistent with that of its conditional

expectation, in particular with respect to $\mathcal{G} = \{\phi, \Omega\}$, and also when $\Gamma \rightarrow E\Gamma$ is viewed as an integral on a space of closed sets it could generate an element that it is not an element of that space.)

Application

Consider the *stochastic optimization problem*:
find

$$\inf E[f(\omega, x_1(\omega), x_2(\omega))] \text{ over all } x_1 \in \mathcal{L}_{n_1}^\infty(\mathcal{G}), x_2 \in \mathcal{L}_{n_2}^\infty(\mathcal{A}), \quad (21)$$

where \mathcal{A} and \mathcal{G} are as before, and f is an \mathcal{A} -normal convex integrand which satisfies the norm-continuity condition:
there exists

$$(x_1^0, x_2^0) \in \mathcal{L}_{n_1}^\infty(\mathcal{G}) \times \mathcal{L}_{n_2}^\infty(\mathcal{A})$$

at which I_f is finite and norm continuous. Suppose also that the effective domain multifunction

$$\omega \rightarrow \text{dom} f(\omega, \cdot, \cdot) = \{(x_1, x_2) \in R^{n_1} \times R^{n_2} \mid f(\omega, x_1, x_2) < +\infty\}$$

is uniformly bounded and that there exists a summable function $h \in \mathcal{L}^1(\mathcal{A})$ such that $(x_1, x_2) \in \text{dom} f(\omega, \cdot, \cdot)$ implies that $|f(\omega, x_1, x_2)| \leq h(\omega)$. Finally suppose that the multifunction

$$\omega \rightarrow D_1(\omega) = \text{cl} \{x_1 \in R^{n_1} \mid \exists x_2 \in R^{n_2} \text{ such that } f(\omega, x_1, x_2) < +\infty\}$$

is \mathcal{G} -measurable. For a justification and discussion of these assumptions cf. [11, Section 2]. From Theorem 1 of [11], it follows that the problem: find

$$\inf E[g(\omega, x_1(\omega))] \text{ over all } x_1 \in \mathcal{L}_{n_1}^\infty(\mathcal{G}), \quad (23)$$

where

$$g(\omega, x_1) = E^{\mathcal{G}}[\inf_{x_2 \in R^{n_2}} f(\cdot, x_1, x_2)](\omega),$$

is equivalent to (21) in the sense that if (\bar{x}_1, \bar{x}_2) solves (21), then \bar{x}_1 solves (23), and similarly any solution x_1 of (23) can be "extended" to a solution (x_1, x_2) of (21). Both problems also have the same optimal value.

The hypotheses imply that

$$(\omega, x_1) \mapsto \inf_{x_2} f(\omega, x_1, x_2)$$

is an \mathcal{A} -normal convex integrand, since the multifunction $\omega \rightarrow \text{epi}(\inf_{x_2} f(\omega, x_1, x_2))$ is closed-convex-valued and \mathcal{A} -measurable. Its effective domain multifunction, or more precisely

$$\omega \mapsto D_1(\omega) = \text{cl dom } q(\omega, \cdot),$$

is \mathcal{G} -measurable. Combining (11) with the representation for the subgradients of infimal functions [15, VIII.4], we have that for every $x_1 \in \mathcal{L}_n^\infty(\mathcal{G})$

$$\begin{aligned} \partial q(\cdot, x_1(\cdot)) &= E^{\mathcal{G}}\{v(\omega) \mid (v(\omega), 0) \in_{\text{a.s.}} \partial f(\omega, x_1(\omega), x_2) \\ &\text{for some } x_2 \in R^{n^2}\}(\cdot), \end{aligned}$$

from which Theorem 2, the main result of [11], follows directly.

Remark If the underlying probability measure P has finite support, then $(\mathcal{L}_n^\infty)^* = \mathcal{L}_n^1$, and (11) and (20) are satisfied without any other restriction.

On the other hand, if P is nonatomic, and the effective domain multifunction (or its closure) is not \mathcal{G} -measurable, then the identities (11) and (20) do not apply. More precisely, suppose that there exists a subset C of R^n such that the \mathcal{A} -measurable set

$$\{\omega \mid \text{dom } f(\omega, \cdot) \cap C \neq \emptyset\}$$

has (strictly) positive mass and is not \mathcal{G} -measurable. Then the term $rc[\partial I_{E^{\mathcal{G}}f}(x)]$ can never be dropped from the representation of $\partial I_{E^{\mathcal{G}}f}$ given by (8), as can be seen from an adaptation of the arguments in Section 4 of [10]. In those cases the inclusion $E^{\mathcal{G}}\partial f \subset \partial E^{\mathcal{G}}f$ will be strict for at least some $x \in \mathcal{L}_n^\infty(\mathcal{G})$.

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