

Old REU lessons: extensions to non circular planar examples

(1)

1) Determinant formula & boundary spike formula

$$\det A(P, Q) \cdot \det K(I, J) = (-1)^k \sum_{\tau \in S_k} \text{sgn}(\tau) \left\{ \sum_{\substack{\alpha \in \mathbb{Z} \\ \alpha = \tau}} \prod_{e \in E_\alpha} \gamma(e) \right\} \det K(I_\alpha, O_\alpha)$$

\uparrow edges in α

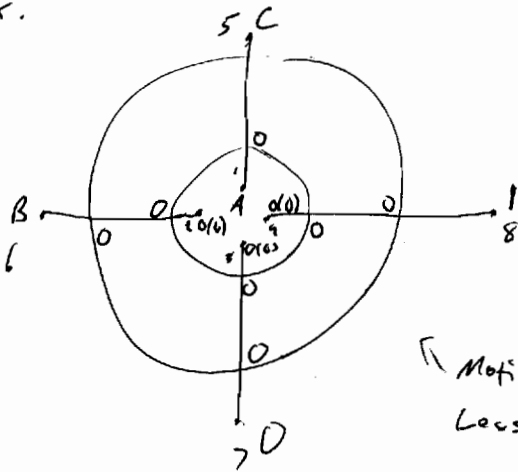
\uparrow unused interior nodes

$\Rightarrow (-1)^k \det A(P, Q) \geq 0$ for cp networks

• Connection \Rightarrow det is nonzero in cp case, but not in general

Adds wrinkle to recovery algorithms for non cp networks

Ex:



$Q = [2 \ 3 \ 4]$ zero current conditions

$P = [1 \ 6 \ 5]$ unknown potentials

$p = 8$ location of potential 1

Motivation: solve for boundary spike
 Lesson: could have used boundary spike formula since contracting spike breaks all P, Q connections and $A(P, Q)$ invertible

First, solving for $\begin{bmatrix} A \\ B \\ C \end{bmatrix}$

$$\vec{0} = A(Q, [P \ p]) \begin{bmatrix} A \\ B \\ C \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} A \\ B \\ C \end{bmatrix} = -A(Q, P)^{-1} A(Q, p)$$

Not enough for connection to exist, need to make sure signs don't cancel to conclude invertibility

Possible connections: $2, 3, 4 \rightarrow 1, 6, 5$
 $\rightarrow 6, 5, 1$

even permutation $\Rightarrow \text{sgn}(\tau)$ stays the same for both \Rightarrow invertible

Connection to boundary spike formula:


Current at spike is $\Delta(p, [P, p]) \begin{bmatrix} A \\ B \\ C \\ I \end{bmatrix} = \Delta(p, p) - \Delta(p, p) \Delta(Q, p)^{-1} \Delta(Q, p)$

potential difference is 1, hence $\gamma = \text{above formula} = \text{current}$

Interesting note: formula \Rightarrow 0 potential at spike's inter-node
~~for that current~~ those boundary conditions.

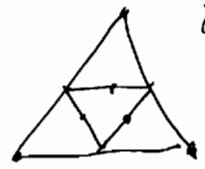
Other comparisons:

non recoverable \nrightarrow γ - Δ equiv to series or parallel in non- γ case

Ex:  infinite to 1 despite 15 equations + 15 unknowns

Recently lots of work on networks whose $\gamma \rightarrow \Delta$ maps are n to 1 for n other than 1 or ∞ , which is all that can happen in γ case.

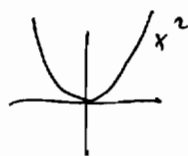
Ex: $\gamma \rightarrow \Delta$ map is 2 to 1



Rank of differential of $T: \gamma \rightarrow \Delta$ gives interesting info

- rank = 12 \Rightarrow locally 1-1, corresponds to globally 2-1
- rank = 11 ~~not~~ (not full) \Rightarrow not locally invertible, but corresponds to set of γ where T is 1-1

$T|_{f(\gamma)=0}$ is 1-1

Interesting analogy:  full rank \Rightarrow globally 2-1, locally 1-1
 not full rank \Rightarrow globally 1-1, not locally invertible

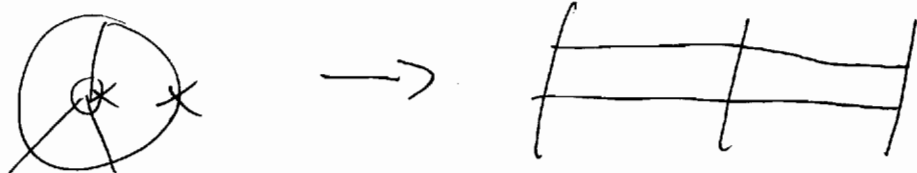
Also $x \geq 0 \Rightarrow$ 1-1 and it turns out $T|_{f(\gamma) \geq 0}$ is 1-1

Another trick for extending cp analysis to non cp case

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Set some γ to 0.

Ex: if $g(\lambda) = 0$ is relation in response matrix,
it still holds if some γ are set to 0



Turns out: same difference of dets is
zero in both networks, although
each is zero in the cp networks.

Problem ideas and some connections to other topics

Edge-node adjacency matrix sometimes useful: A is edges by nodes

$$A_{ek} = \begin{cases} \pm 1 & \text{if edge } e \text{ connected to node } k \\ 0 & \text{otherwise} \end{cases}$$

(arbitrary)
Convention about orientation of edges: if e connected to i, j and $i < j$ then $A_{ei} = 1, A_{ej} = -1$

(Ting, Sam, George used for some numerical formulations and to help simplify work about rank of differential)

Define $C =$ diagonal matrix with conductances γ_e on diagonal

Then Kirchhoff matrix $K = A^T C A$, direct analogue to $-\nabla \cdot (\sigma \nabla)$
 $A \sim \nabla, A^T \sim -\text{div}, C \sim \sigma$

Any additional insight about Δ ?

Index $A = \begin{bmatrix} E & F \end{bmatrix}$ according to boundary, interior nodes. $K = \begin{bmatrix} A & B \\ B^T & D \end{bmatrix}$

$$K = \begin{bmatrix} E^T \\ F^T \end{bmatrix} \begin{bmatrix} C \end{bmatrix} \begin{bmatrix} E & F \end{bmatrix} = \begin{bmatrix} E^T C E & E^T C F \\ F^T C E & F^T C F \end{bmatrix}$$

$$\Delta = A - B D^{-1} B^T = E^T C E - E^T C F (F^T C F)^{-1} F^T C E$$

$$= E^T C^{\frac{1}{2}} \underbrace{\left(I - C^{\frac{1}{2}} F (F^T C F)^{-1} F^T C^{\frac{1}{2}} \right)}_P C^{\frac{1}{2}} E$$

$P =$ orthogonal projection onto $\text{im}(C^{\frac{1}{2}} F)^\perp = \text{Ker}(F^T C^{\frac{1}{2}})$

$P = Q Q^T$ where columns of Q form orthonormal basis for $\text{im}(C^{\frac{1}{2}} F)^\perp$

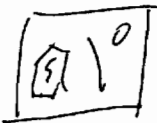
$$\Delta = E^T C^{\frac{1}{2}} Q Q^T C^{\frac{1}{2}} E = (Q^T C^{\frac{1}{2}} E)^T (Q^T C^{\frac{1}{2}} E)$$

graph interpretation

power dissipated = $x_B^T \Delta x_B = \| Q^T C^{\frac{1}{2}} E x_B \|^2$

Using the forward problem for image segmentation

Talk by Leo Grady about this.

Problem: segment  given use input of some labels

Define lattice network with "conductances" such that high conductance between similar intensities and low conductance between dissimilar intensities.

Normalize K by $W^{-1/2} K W^{-1/2}$ where $W = \text{diag}(K)$
Assume K already normalized.

Assign labels to nodes by randomly walking and seeing which labels ~~hit first~~ most likely to be hit first.

Use equivalence between random walks & forward problem.

$K = \begin{bmatrix} A & B \\ B^T & D \end{bmatrix}$ $1 = -D^{-1} B^T 1 = -D^{-1} B^T (s_1 + \dots + s_k)$ can treat as probabilities...
← k labels, potential 1 on label, 0 elsewhere

$x_i = \begin{cases} 1 & \text{at int node } i \\ 0 & \text{at other int nodes} \end{cases}$

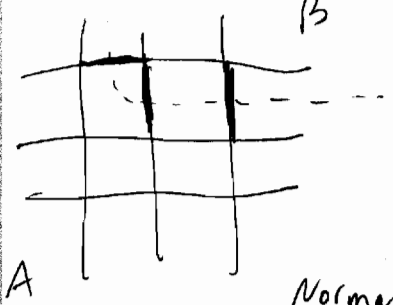
Then $-x_i^T D^{-1} B^T s_j$ is probability of random walk from x_i hitting s_j first

Transition matrix $T = \begin{bmatrix} I & -B \\ 0 & I - D \end{bmatrix}$

Same prob is $+ [s_j^T \ 0] \lim_{n \rightarrow \infty} T^n \begin{bmatrix} 0 \\ x_i \end{bmatrix}$ $T^n = \begin{bmatrix} I & -B(I + (I-D) + (I-D)^2 + \dots) \\ 0 & (I-D)^n \end{bmatrix}$

Neumann series $\rightarrow \begin{bmatrix} I & -B D^{-1} \\ 0 & (I-D)^n \end{bmatrix}$ if deg ≥ 2 for int nodes
 $= -s_j^T B D^{-1} x_i = -x_i^T D^{-1} B^T s_j$

Similar to normalized cuts: Shi-Malik
Related



$$\text{cut}(A, B) = \sum_{u \in A, v \in B} w(u, v)$$

find partition that minimizes

maybe some constraints on sizes of A, B ...

Normalized version: $\frac{\text{cut}(A, B)}{|A|} + \frac{\text{cut}(A, B)}{|B|}$

$| \cdot |$ = total weights in partition

Unfortunately: NP hard

Fortunately: Similar to $\min \frac{\sum_{i,j} (v_i - v_j)^2 w_{ij}}{\sum_i w_i v_i^2}$ st $v \perp \mathbf{1}$

$$v = W^{-1/2} z$$

$$\Rightarrow \min \frac{z^T W^{-1/2} K W^{-1/2} z}{z^T z} \text{ st } z \perp W^{1/2} \mathbf{1}$$

Raleigh quotient

eigenvector for smallest eigenvalue, 0_1 of normalized graph lap

minimizer is eigenvector for second smallest eigenvalue

$$\Rightarrow \text{2nd smallest generalized ev} \text{ for } K v = \lambda W v$$

diagonal weights

For the numerics of segmentation using Dirichlet prob; the evs for the smallest evs are most important

Krylov methods for evc iteration ...

Numerics for recovering γ in electrical networks:
continue work by Sam, Ting, George 2006

Many different numerical approaches

Ex: They had good success minimizing $\|\Delta(\gamma) - \Delta\|^2$ via Levenberg-Marquadt
(somewhere between Gauss-Newton & gradient descent, w/ regularization)

Still questions:

How to regularize γ ?
piecewise constant $\Rightarrow \sum_{i,j,i,k} \bar{\gamma}_{ij} (\gamma_{ij} - \gamma_{ik})^2$
known values \Rightarrow round to correct

Something else? Maybe power dissipated $x_B^T \Delta(q) x_B$

Can use extra measurements:

$$G(q) = \sum_i \|\phi_{B_i}(q) - \phi_{B_i}\|^2 \quad \text{for associated imposed } x_{B_i}$$

Stick trick for differentiating $\Delta(q)$ wrt q
 $\phi_B = \Delta x_C = \underbrace{A x_B}_{E^T C} + \underbrace{B x_C}_{E^T C}$ remark...

Different trick for simplifying derivative wrt q is to add interior potentials as extra variables

$$G(q, x_I) = \sum_{i=1}^N \|\phi_{B_i}(q, x_{I_i}) - \phi_{B_i}\|^2 \quad \text{constrain } \phi_{I_i}(q, x_{I_i}) = 0 \quad i=1, \dots, N$$

No inverses required to compute derivs wrt q or x_I .

But many more variables...

L-M: $f = \frac{1}{2} \sum F_i^2 \Rightarrow f' = J^T F$, F is vectorized $(\Delta(q) - \Delta)$

$J^T J$ approximates Hessian

$$(J^T J + \alpha_k I) d_k = -J^T F \text{ solves for search direction}$$

\Rightarrow $f(x_k + \alpha d_k) < f(x_k)$ for some α
update

000 problems:

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• Find Network

$$\delta = 0 \text{ or } 1$$

• See Strang talk or paper for interesting max flow / min cut problems

Interesting because of dual approaches

$$\text{Ex: Max } x \text{ s.t. } Ax = b, |x_i| \leq c_i$$

Equivalent to

$$\text{Min } \sum_i (A_{ij})_i |c_i \text{ s.t. } ab = 1$$

↑

~ $\sum (u_j - u_i) |c_{ij}$ in node notation